

Software code

```
/*Code for data logging for Arduino with Atmega328 chip and 3 differential pressure sensors MPX5100DP mounted on tensiometers for monitoring water potential in soils.
```

After powering, the tensiometer station serial connection can be established either from within the *Arduino* IDE (serial monitor) or using a third-party software (e.g. Hyper Terminal). Set the baud rate to 9600 bps. A user menu will appear when typing the character "x", listing the following options, which can be selected by typing the appropriate letter:

s (status) --> displays momentary tensiometer values and various programme parameters

t (transfer data) --> start data transfer from *Arduino* to PC

e (erase memory) --> erase all data stored in the *Arduino* EEPROM

h (set time) --> set the time of the *Arduino* software clock

d (set date) --> set the date of the *Arduino* software calendar

i (set recording interval) --> set the time interval at which tensiometer recording should take place

b (set blink threshold) --> set the tensiometer value threshold at or above which the LED should start blinking

*/

```
#include <EEPROM.h> // this library is needed for writing/reading data to/from the  
atmega's EEPROM
```

```
const int powerpins[]={10,11,12}; //this array lists the digital pins used for supplying power  
to the pressure sensors – avoid using digital pins 0 and 1.
```

```
const int tensiopins[]={0,1,2}; //this array specifies the analogue pins which measure  
sensor output. Current is provided to the sensors from the digital pins listed in the same  
sequential order as in the array "powerpins". A maximum of 6 sensors can be connected  
(AD ports 0-5).
```

```
const int offset=10; //this corresponds to the typical value of 0.2V for the calibration offset  
of the MPX5100DP sensor.
```

```
/*
```

This is an example code for 3 tensiometers. To change the number of tensiometers,
simply declare less or more digital and analoueg pins in the respective arrays:

example 1: a 2-tensiometer configuration:

```
int powerpins[]={3,4};  
int tensiopins[]={0,1};
```

example 2: a full configuration with 6 tensiometers:

```
const int powerpins[]={3,4,5,6,7,8};  
const int tensiopins[]={0,1,2,3,4,5};  
*/
```

```
int mem_counter; //counter for available memory  
int time;  
int _MINUTE=0;  
int _HOUR=0;  
int value;  
long minute_counter;
```

```
int _DAY=1;  
int _MONTH=1;  
  
const int month_days[12]={  
    31,28,31,30,31,30,31,31,30,31,30,31}; //this array contains the length (no. of days) of  
each month  
  
const int tensionumber=(sizeof(tensiopins)/2); //determine the number of tensiometers  
from the number of ports listed in the array "tensiopins"  
  
const int led_pin=13; // Pin 13 is connected to a LED on most Arduino boards  
  
int threshold=300; //variable for threshold of soil water tension at or above which the LED  
will start blinking; default = 300 hPa  
  
int interval; // variable for the time interval between successive tensiometer recordings  
  
byte blinkflag=0; //flag indicating whether tensiometer threshold has been reached  
  
  
void setup()  
{  
    for (int i=0; i < tensionumber; i++){ //set the digital pins as output  
        pinMode(powerpins[i], OUTPUT);  
    }  
    pinMode(led_pin, OUTPUT);  
  
    minute_counter=(millis() / 60000); //set minute counter to initial value  
  
    delay(1000);  
  
    Serial.begin(9600);  
  
    delay(1000);  
  
    mem_count_retrieve(); //retrieve the last stored value of the memory counter from  
EEPROM  
  
    check_interval(); //look up the logging interval from EEPROM
```

}

void loop()

{

time = _HOUR;

while(time==_HOUR) {

if (blinkflag==1) { //if the tensiometer threshold has been reached, start blinking the LED

blinkloop();

}

simple_clock();

if (Serial.available() > 0) {

checkrx();

}

}

tensio_record();

}

void simple_clock(){

if (millis() / 60000 != minute_counter) {

minute_counter=(millis() / 60000);

_MINUTE++;

```
/*60000 millis make a minute; however there might be variations due to differences  
between
```

```
individual quartzes/resonators mounted on the boards. If the clock runs too fast, increase  
this value in the 2 programme lines above, if the clock runs too slow, reduce it
```

```
*/
```

```
if(_MINUTE>59) {  
    _MINUTE=_MINUTE-60;  
    _HOUR++;  
}
```

```
if(_HOUR>23)  
{  
    _HOUR=0;  
    _DAY++;  
}
```

```
if(_DAY>month_days[_MONTH-1]) //check if end of the month has been reached  
{  
    _DAY=1;  
    _MONTH++;  
}
```

```
if(_MONTH>12)
```

```
{  
    _MONTH=1;  
}  
}  
}
```

```
void checkrx()  
{  
    if (Serial.read()==120) { //if the character is "x", display the menu  
        menu();  
    }  
    else {  
        Serial.println("no access");  
    }  
    Serial.flush(); //empty serial buffer  
}
```

```
void menu()  
{  
    Serial.println("*****");  
    Serial.println("s - status");  
    Serial.println("t - transfer data");  
    Serial.println("e - erase memory");  
    Serial.println("h - set time");  
    Serial.println("d - set date");  
    Serial.println("i - set logging interval");
```

```
Serial.println("b - set blink threshold");

Serial.println("*****");
while (Serial.available() == 0){

} //wait for command over serial port

if (Serial.available()>0) {

    value = Serial.read();

}

if (value == 'h') { //h-set time

    set_time();

}

if (value == 'd') { //d-set date

    set_date();

}

if (value == 't') { //t-transfer data

    read_memory();

}

if (value == 's') { //s-status

    actual_read();

}

if (value == 'e') { //e-erase memory

    clear_memory();

}

if (value == 'b') { //b-blink threshold

    set_threshold();

}

if (value == 'i') { //i-set logging interval
```

```
set_interval();

}

}

void tensio_record() { //for each tensiometer take 10 readings and calculate the mean
blinkflag=0;

for (int i=0; i <tensionumber; i++){
    digitalWrite(powerpins[i], HIGH); //power up sensor
    delay(50); //warming up of MPX5100DP
    int value = 0;
    for (int j=0; j <= 9; j++){ //take 10 readings and calculate mean value
        value=value + analogRead(tensiopins[i]);
        delay(100);
    }
    digitalWrite(powerpins[i], LOW); //power off
    value=value/40; //mean value divided by 4 to reduce from 10 to 8 bit

    if(((value-offset)*5.00/256)/45*10000)>=threshold) { //if tensiometer reading in hPa is
equal or higher than the threshold value (both as absolute values), start blinking the LED
    blinkflag=1;
}

if (mem_counter < 1024) { //back to loop if memory space is exhausted
interval=EEPROM.read(4); //retrieve value of interval from EEPROM
if (_HOUR%interval==0 || _HOUR==0) { //if the set time interval has been reached, store
tensiometer readings in EEPROM
    EEPROM.write(mem_counter, value);
}
```

```
mem_counter = mem_counter+1;  
mem_count_write();  
}  
}  
}  
}
```

```
void set_time(){  
Serial.print("hour(00-23): ");  
make_number();  
if (value>=0 && value<24) {  
_HOUR = value;  
}  
Serial.print("minute(00-59): ");  
make_number();  
if (value>=0 && value<60) {  
_MINUTE = value;  
}  
write_time();  
}
```

```
void set_date(){  
Serial.print("day(01-31): ");  
make_number();  
if (value>=0 && value<=31) {  
_DAY = value;
```

```
}

Serial.print("month(01-12): ");

make_number();

if (value>=0 && value<=12) {

_MONTH = value;

}

write_time();

}

void set_threshold(){

Serial.print("threshold: ");

Serial.println(threshold);

Serial.print("new threshold/10: (00-60) "); //e.g. to set the threshold to 500, enter 50

make_number();

if (value>=0 && value<=60) { //possible threshold range is 0 - 600 hPa

threshold = value*10;

}

Serial.println(threshold);

}

void read_memory(){

Serial.println("start logging (dd/mm h:min):");

Serial.print(int(EEPROM.read(2)));

Serial.print("/");

Serial.print(int(EEPROM.read(3)));

Serial.print(" ");

}
```

```
Serial.print(int(EEPROM.read(0)));

Serial.print(":");

if((int(EEPROM.read(1))<10) {

    Serial.print("0");

}

Serial.println(int(EEPROM.read(1)));

Serial.print("logging interval (h): ");

interval=EEPROM.read(4); //retrieve the last stored value of the logging interval

Serial.println(interval);

Serial.println("tensiometer readings:");

for (int i=1; i<=tensionumber; i++){

    Serial.print("T");

    Serial.print (i);

    if (i%tensionumber==0) { //one column for each tensiometer

        Serial.println("");

    }

    else {

        Serial.print("\t");

    }

}

mem_count_retrieve();

int j=0;

for (int i=7; i<=(mem_counter-1);i++){

    Serial.print(int(((EEPROM.read(i)-offset)*5.00/256)/45*10000)); //read from memory

and transform to hPa
```

```
j++;

if (j%tensionumber==0) {

    Serial.println("");

}

else {

    Serial.print("\t");

}

delay (30); //delay for reducing speed of data transfer to avoid serial overflow

}

Serial.println("data transfer complete");

write_time();

}

void residual_memory(){

mem_count_retrieve();

interval=EEPROM.read(4); //retrieve the last stored value of the logging interval

value=(1023-mem_counter)/tensionumber/(24/interval);

Serial.print("remaining memory: ");

Serial.print(value);

Serial.print(" days ");

value=(((1023-mem_counter)/tensionumber)%(24/interval));

Serial.print(value);

Serial.println(" hours");

}
```

```
void actual_read() {
    Serial.println("actual values (hPa):");
    for (int i=0; i <tensionumber; i++){
        digitalWrite(powerpins[i], HIGH);
        delay(50);

        int value = 0;
        for (int j=0; j <= 9; j++){
            value=value + analogRead(tensiopins[i]);
            delay(100);
        }
        digitalWrite(powerpins[i], LOW);
        value=value/40;
        value=value-offset;
        if(value<0) //avoiding negative numbers
        {value=0;
        }
        Serial.print(int((value*5.00/256)/45*10000)); //transformation of reading into hPa
    according to calibration function
    if ((i+1)%tensionumber==0) {
        Serial.println();
    }
    else {
        Serial.print("\t");
    }
}
Serial.print("blink threshold (hPa): ");
```

```
Serial.println(threshold);
Serial.print("logging interval (h): ");
interval=EEPROM.read(4); //retrieve the last stored value of the logging interval
Serial.println(interval);
residual_memory(); //display the available memory for data logging
write_time();
}
```

```
void make_number(){
int a;
int b;
while (Serial.available() == 0){
} //wait for data from serial port
if (Serial.available()>0) {
```

```
    a = Serial.read();
}
```

```
Serial.print(a-48);
```

```
while (Serial.available() == 0){
}
```

```
if (Serial.available()>0) {
```

```
    b = Serial.read();
}
```

```
Serial.println(b-48);
```

```
value=((a-48)*10+b-48);
```

}

```
void write_time(){  
    Serial.print("date: ");  
    Serial.print(_DAY);  
    Serial.print("/");  
    Serial.println(_MONTH);  
    Serial.print("time: ");  
    Serial.print(_HOUR);  
    Serial.print(":");  
    if (_MINUTE<10) {  
        Serial.print("0");  
    }  
    Serial.println(_MINUTE);  
}
```

```
void mem_count_retrieve() {  
    mem_counter=EEPROM.read(5)*256+EEPROM.read(6);  
}
```

```
void clear_memory() {  
    Serial.println("sure? y/n");  
    while (Serial.available() == 0){  
    } //wait for data from serial port  
    if (Serial.read()==121) { //y  
        mem_counter=7; //the first 7 bytes of the EEPROM are reserved for storing variables
```

```
mem_count_write();

EEPROM.write(0,_HOUR); //save hour to address 0

EEPROM.write(1,_MINUTE); //save minutes to address 1

EEPROM.write(2,_DAY); //save day to address 2

EEPROM.write(3,_MONTH); //save month to address 3

EEPROM.write(4,interval); //save logging interval to address 4

Serial.println("memory cleared");

}

Serial.flush(); //empty serial buffer

}
```

```
void mem_count_write() { //write value of memory counter to EEPROM

EEPROM.write(5, mem_counter/256);

EEPROM.write(6, mem_counter%256);

}
```

```
void blinkloop() {

digitalWrite(led_pin, HIGH); // set the LED on

delay(500); // wait

digitalWrite(led_pin, LOW); // set the LED off

delay(1500); //wait

}
```

```
void set_interval(){ //a newly set interval will only become effective after clearing the
memory with the appropriate function in the menu

Serial.print("interval (h): ");
```

```
Serial.println(interval);
Serial.println("new interval (01-02-03-04-06-08-12-24) ");
make_number();
if (value==1 || value==2 || value==3 || value==4 || value==6 || value==8 || value==12 ||
value==24){
    interval = value;
}
Serial.print("new interval: ");
Serial.println(interval);
Serial.println("clear memory to make change effective!");
}

void check_interval() {
    value=EEPROM.read(4); //retrieve the last stored value of the logging interval
    if (value==1 || value==2 || value==3 || value==4 || value==6 || value==8 || value==12 ||
value==24){
        interval = value;
    }
    else { //if no value for the logging interval is set, use 1h as default
        interval=1;
        EEPROM.write(4,interval); //save logging interval to address 4
    }
}
```